

# KAISER HAMID

Lubbock, Texas

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## EDUCATION

<b>Texas Tech University (TTU)</b> <i>PhD in Industrial Engineering</i>	<b>Aug 2024 - Present</b> <i>Lubbock, TX</i>
<b>Texas Tech University (TTU)</b> <i>MS in Electrical and Computer Engineering (ECE)</i>	<b>Aug 2024 - Present</b> <i>Lubbock, TX</i>
<b>Bangladesh University of Engineering &amp; Technology (BUET)</b> <i>BSc. in Civil Engineering</i>	<b>Apr 2019 - Jul 2024</b> <i>Dhaka, Bangladesh</i>

## WORK EXPERIENCE

<b>Graduate Research Associate</b> <i>Autonomous Driving, Computer Vision, Human Factors</i> <ul style="list-style-type: none"><li>• <b>Advisor: Dr. Nade Liang</b></li></ul>	<b>Aug 2024 - Current</b> <i>Lubbock, Texas</i>
<b>Research Associate</b> <i>Deep Learning, App Development, Database Management</i> <ul style="list-style-type: none"><li>• <b>Advisor: Dr. Annesha Enam</b></li></ul>	<b>Dec 2022 - Jul 2024</b> <i>Dhaka, Bangladesh</i>

## TECHNICAL SKILLS

**Languages:** Python, C, C++, Dart, R, MATLAB  
**Developer Tools:** VS Code, Android Studio  
**Technologies/Frameworks:** GitHub, ReactJS, NodeJS, Git, Mongo, Flutter  
**Deep Learning Frameworks:** TensorFlow, Keras, PyTorch  
**Libraries:** Scikit-learn, Pandas, Numpy, Scipy, OpenCV, Matplotlib, Seaborn  
**Simulation tool for autonomous driving:** CARLA

## RESEARCH INTERESTS

Autonomous driving, Computer vision, Human factors.

## Publications

### Peer-Reviewed Conference Papers

- **Hamid, K.**, Noor, M. S., Enam, A. "Assessing the Potential of Google Location History (GLH) Data for Travel Behavior Research in the Context of Developing Country." Proceedings of the 27th IEEE International Conference on Intelligent Transportation Systems (ITSC 2024).

### Manuscripts Under Review

- **Hamid, K.**, Liang, N. "Predicting the Next Move: A Systematic Review of Driver Intention Modeling for Autonomous Vehicles." [Under review]
- **Hamid, K.**, Akbar, K. A., Liang, N. "FSDAM: Few-Shot Driving Attention Modeling via Vision-Language In-Context Learning." [Under review]
- **Hamid, K.**, Liang, N. "A New Evaluation Metric for Takeover Maneuver Quality: Comparing Human Drivers with Autonomous Driving Agents." [Under review]

## GRANTS AND AWARDS

- **Research Grant, CASR (JULY, 2024):** Awarded a prestigious \$2500 research grant for work on Google Location History.
- **Graduate College Travel Award (SEPTEMBER, 2024):** Received \$950 to attend the IEEE ITSC Conference (2024-25).

## PROJECTS

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- **Pedestrian Detection using Deep Learning:** Developed a pedestrian detection system utilizing deep learning models.  
**Technologies:** Python, Google Colab [Watch Demo]
- **Traffic Mode Detection & Tracking for Dhaka, Bangladesh:** Built a traffic mode detection and tracking system for urban mobility analysis.  
**Technologies:** Python, Google Colab [Watch Demo]
- **Gulshan-1 Intersection Simulation for CAPSTONE Project:** Simulated traffic flows at a major intersection to analyze and optimize performance.  
**Technologies:** VISSIM Software [Watch Demo]
- **Traffic Mode Detection for Dhaka, Bangladesh:** Created a detection system to classify and analyze traffic modes in Dhaka.  
**Technologies:** Python, Google Colab [Watch Demo]
- **Trip Tracker App for Collecting User Data:** Designed and implemented a mobile app to collect and analyze user trip data.  
**Technologies:** Flutter, MongoDB [Watch Demo]
- **CARLA HITL (Human In The LOOP):** Designed framework to work with steering, pedal and gear box with data logging  
**Technologies:** Unreal Engine [Watch Demo]
- **Raspberry Pi 4 Data Logger with CAN Bus:** Developed a compact system using Raspberry Pi 4 to interface with vehicle CAN bus for real-time data logging and sensor integration  
**Technologies:** Raspberry Pi 4, CAN bus, Python [Watch Demo]

## Selected Courses

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Pattern Recognition, Machine Learning, Advanced Cognitive Systems, Design of Experiments, Image Processing.

## Professional Service

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- **Manuscript Reviewer**, Human Factors and Ergonomics Society (HFES) Annual Meeting, 2025
- **Manuscript Reviewer**, Transportation Research Board (TRB) Annual Meeting, 2026